# SIEMENS

Data sheet for SINAMICS G120C

### Article No. :

## 6SL3210-1KE21-3AF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	% -20 %
Line frequency	47 63 Hz	
Rated current (LO)	16.50 A	
Rated current (HO)	12.80 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC <sup>1)</sup>
Rated power (LO)	5.50 kW	7.50 hp
Rated power (HO)	4.00 kW	5.00 hp
Rated current (LO)	12.50 A	
Rated current (HO)	8.80 A	
Rated current (IN)	13.00 A	
Max. output current	17.60 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

#### **Overload capability**

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor $\lambda$	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	173.0 W	
Filter class (integrated)	Class A	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	1		
Output (resistive load)	DC 30 V, 0.5 A		
Number as transistor	1		
Output (resistive load)	DC 30 V, 0.5 A		
Analog / digital inputs			
Number	1 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$			
Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		

Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



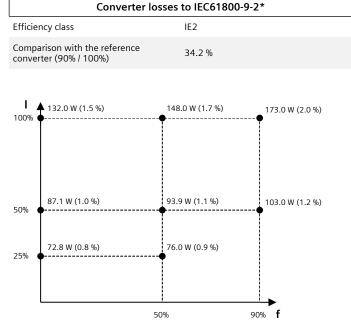
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Ambi	ent conditions
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.009 m³/s (0.318 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Co	onnections
Signal cable	
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Line side	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm <sup>2</sup> (AWG 12 AWG 10)
Motor end	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
DC link (for braking resistor)	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw
Max. motor cable length	
Shielded	50 m (164.04 ft)
Unshielded	100 m (328.08 ft)
Мес	hanical data
Degree of protection	IP20 / UL open type
Frame size	FSB
Net weight	2.30 kg (5.07 lb)
Dimensions	
Width	100 mm (3.94 in)
Height	196 mm (7.72 in)
Depth	208 mm (8.19 in)
	Standards
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*converted values

 $^{\rm 1)} {\rm The}$  output current and HP ratings are valid for the voltage range 440V-480V